



# Complex Adaptive Systems: an Introduction

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# About Me...

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- Professor in Computer Science
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  - [franco.zambonelli@unimore.it](mailto:franco.zambonelli@unimore.it)
- Expertise in distributed systems engineering
  - And in particular in the application of complex and adaptive systems solutions to distributed computing
  - 3 books, about 150 scientific papers
  - International awards
  - Coordinator of several EU projects on the theme
- Teaching
  - Complex adaptive systems
  - Operating systems and Java programming



# About this Course

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- Trying to give answers to the following questions:
  - What are complex adaptive systems (CAS)?
  - How do they work?
  - Why are they important for modern ICT systems?
  - Technologies that now more closely approach CAS (multiagent systems and swarm intelligence)
- And eventually
  - Discover how the lessons of CAS can help us better understanding modern ICT system
  - Learn how to engineer innovative solutions inspired by CAS



# Outline of Today

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- What are CAS? That is...
- What are Systems
  - Components, interactions, dynamics
- What is Adaptivity
  - Openness, situatedness, context-awareness
- What is Complexity
  - Complicated vs. complex Systems
  - Complexity vs. chaos
  - Relations with natural systems
- Why CAS in Modern Distributed Systems are?
  - Characteristics of modern distributed systems
  - Needs for CAS and Self-organization
- The Example of Cellular Automata
- Complex Networks and Social Networks



# What are Complex Adaptive Systems?

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- Let's understand this by characterizing the concepts of
  - ***System***
  - ***Adaptivity***
  - ***Complexity***
- Contextualize this to distributed computational systems
- And exemplify with the CA example



# Part 1

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- What is a System?



# What are “Systems”?

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- A System is an ensemble of (situated) individual entities interacting with each other
  - Individual entities:
    - atoms, cells, organs, animals, trees, humans
    - Chips, computers, LANs, sensors robots
  - Interacting
    - Physical forces, protein diffusion, gestures, words
    - Electric Signals, packets, IP datagrams, radio signals
  - Situated
    - Existing in an “environment” (see next)



# Modeling Individuals in a System

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- In general, an entity in a system is characterized by:
- A state
  - The dimensions fully characterizing the current situation of the individual
    - E.g., position and speed ( $X, dX/dt$ ) for a physical object
    - E.g., the value of its instance variables for a software object
    - E.g., the “mood” for a human
- Transition rules
  - What events in the system make an individual change its state
    - i.e., what interactions
    - E.g., a gravitational force, the finding of food, a conversation...
- A Behavior
  - What the individual do in the system, how it affect the system
    - E.g., spreading of a gravitational force, eating food, talking, or simply occupy space
    - An object invoking methods of other objects
    - A Servlet changing a database
- A Context (a “position” in the environment)
  - Sometimes, it is useful to model a system and its individual as being “situated” in some environment
    - E.g., a topological space-time universe, a landscape, a room,
    - A servlet context
  - Other times, the environment in turn is modeled in terms of individuals
    - E.g., the space time being made of gravitons, a landscape being made of individual trees, grass, mote, etc.
    - In an OO program, everything is an object





# Modeling Interactions in a System

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- An interaction is any event in a systems that
  - Caused by an individual in a system
  - Affect that state or one or several individual in the system
- Types of interactions
  - Direct (“Communication”)
    - Two particles colliding with each other
    - Two humans talking with each other
    - A client and a server exchanging TCP packets
  - Indirect (“Stigmergic” or mediated by the environment)
    - The modification of the speed of a particles caused by the gravitational field of another particles
    - The spread of pheromones by ants
    - Playing Chess
    - Two servlets accessing the same Attribute
- A note:
  - Sometimes, mediated interactions are not considered (i.e., fields in modern physics are modeled as particles!)
  - But this may be very important in distributed computational systems!!!



# Distributed Computational Systems

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- A Single computer is a system
  - Many components, to be orchestrated
  - By the operating system
  - Via coordination of access to common resources (stigmergic)
- Computer networks, in general...
  - Individual entities: computers
  - Networks: LAN + Internet
  - Interactions:
    - Direct: Message-passing, Client-server, Events
    - Stigmergic: Access to common databases and resources
- But with a very broad meaning
  - Computers: Supercomputers, PC, PDA, Mobile Phones, embedded computers
  - Networks: Wires, Wireless, GPRS, UMTS, Bluetooth, P2P, The Web, The overlying social networks
  - Interactions: Access to common memory, Access to common artifacts, RF-ID Tags, Broadcasting, Digital Pheromones, Digital fields
  - Will analyse all of these....



# Discrete vs. Continuous & Synchronous vs. Asynch. Systems

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- The modeling of a system may imply
  - Continuous vs. Discrete state
  - Continuous vs. Discrete time
- Global vs. Local Time
  - Global: all the individual of the system have the same clock, and thus perform state transition at the same time
    - **Synchronous**: when they perform state transition at the same time or when there is a sort of global controller for transitions
  - All the individual have individual clocks
    - **Asynchronous**: when they do not obey to global clock rules to perform state transitions, and there is not global controller
- Summarizing:
  - **Physics** is discrete in state, continuous in time, and asynchronous
  - **Ecology** is continuous in state, continuous in time, and asynchronous
  - **Computing** is discrete in time, discrete in time and synchronous
  - **Distributed computing** is discrete in time, discrete in time and asynchronous



# Local vs. Global System State

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- The collection of all states of all individual of a systems (i.e., the **local states**), plus the state of the environment, if needed, determines:
  - The **global state** of the system
- However, in many cases, the global state is represented by more “synthetic” indicators, Because
  - It give a synthetic clue of what is happening in the system
  - Sometimes, it is impossible to determine the global state in terms of all local states
- Examples
  - “The current average speed on the highway is 45mph”
  - “The DISMI network has a throughput of 345kbs”
  - “The unbalance in computer load is 45%”
  - The state of a gas is measured by P & T, because it is impossible to measure the positions and speeds of all its atoms



# System Dynamics

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- A system evolves in time
  - Via the **local** state transition (local state changes) of its individuals
  - Affecting the **global** system state
- The study of system dynamics imply
- Determining the evolution of the system
  - Given an initial state
  - E.g., will the system reach a global equilibrium? Of what type? From what initial states will reach what equilibrium state? Will it continue evolving indefinitely? What happens when we perturb the system from equilibrium?



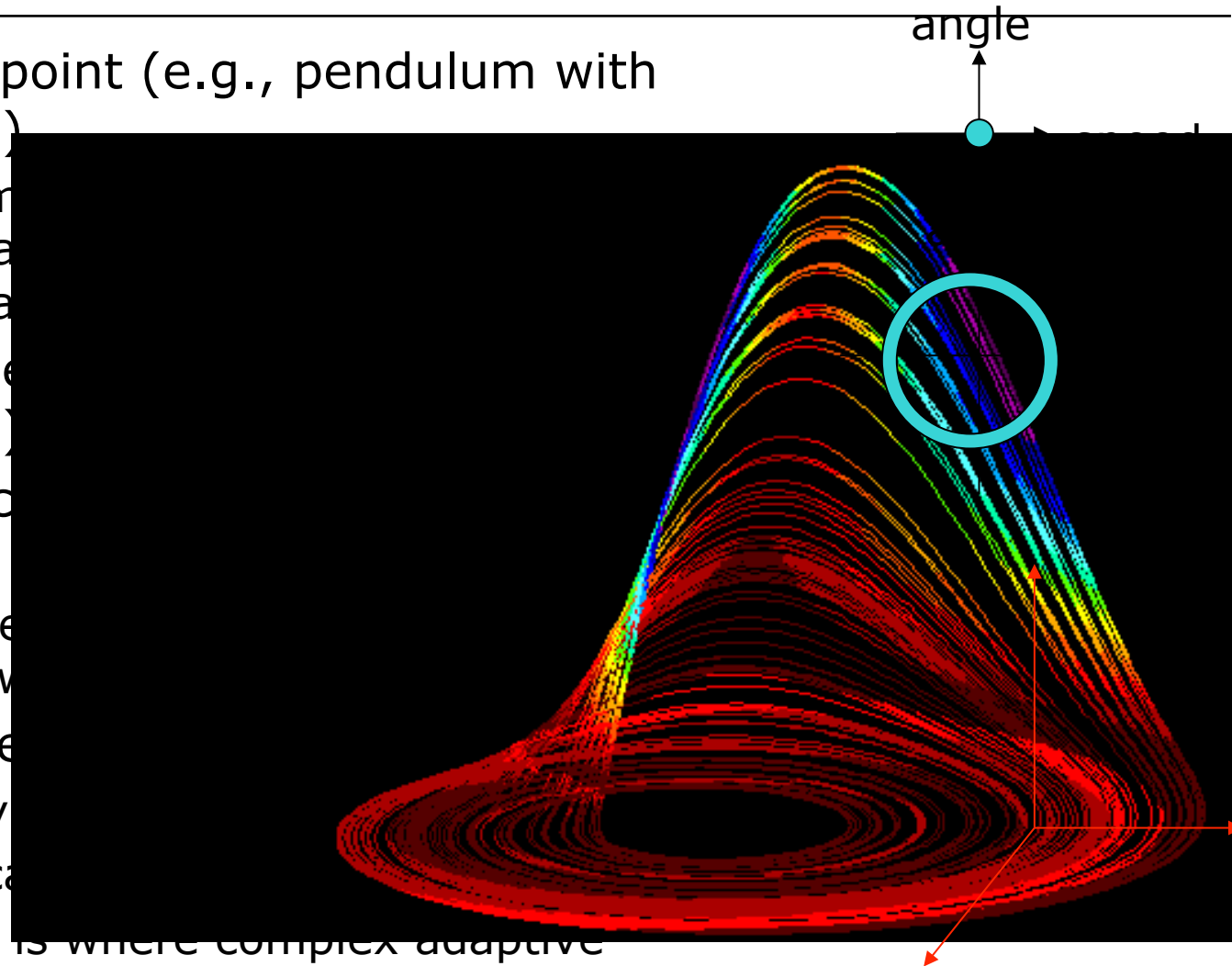
# The “Phase Space” of a System

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- When studying system dynamics, one
  - Does not refer to the evolution in state of all its system components
  - But rather to the evolution of some of its relevant global state indicators
    - E.g., the evolution of a gas is described in terms of how its temperature and pressure change in time
  - This is the so called “trajectory in the state space”
    - The dynamic evolution of the system as a point moving in a n-dimensional diagram, starting from an initial point
    - Axis represent the relevant indicators of the global system state
    - And in which time passes as the point moves...
- Typically, the trajectory tend to be “attracted” in specific regions of the diagram
  - “**Attractors**” of the systems (single points for static equilibrium, circles for periodic behaviours, or more complex manifold)
  - **Attractors express stability**: once the system reaches an attractor, it will stay there indefinitely, until perturbed

# Movements and Attractors in the Phase Space

- Single point (e.g., pendulum with friction)
  - From dynamical system towards a single point
- Cycle (e.g., pendulum without friction)
- Chaotic (e.g., gas)
  - Movement in the phase space is chaotic
- Strange attractor (e.g., Lorenz attractor)
  - Very complex
  - So called chaotic
  - This is where complex adaptive systems stand...





## Part 2

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- What is an Adaptive System?





# What is Adaptivity?

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- The capability of a system and/or of its individuals of tuning its behavior to contingent situations
- Adaptivity implies that the system is both **flexible** and **robust**
  - Re-organizes itself in response to stimuli
  - Preserves the same overall dynamics
  - Preserves (some of) its specific characteristics independently of external contingencies/stimuli
- What are these contingencies requiring adaptivity?
  - **Openness** → the boundaries of a system are open
  - **Environmental Dynamics** → the environment may be dynamic and unpredictable
  - **Structural dynamics** → the components can be themselves dynamic
- In general, one or more of these sources of dynamicity affect all modern distributed computing systems (details later)



# Adaptive vs. Non Adaptive Systems

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- Adaptivity in response to openness and environmental perturbations/dynamics implies
  - **Flexible response:** the system adapt its overall dynamics in response to stimuli
  - **Robust behavior:** at the same time, the system preserve its overall behavior, or at least some of its relevant characteristics
- However, please note that adaptivity is not an absolute concept
  - It depends on what we are interested in in a system
  - It sometimes depends on the eye of the observer and on the level of observation of the system



# Earth vs. Heart

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- The Earth mechanical dynamics
  - Non adaptive: a perturbation (e.g. a big earthquake) change its rotation period permanently
- The Earth climate
  - Very Adaptive: stable over very long periods despite pollution and sun storms
  - But non adaptive from the viewpoint of LA's inhabitants 😊
- The Heart dynamics
  - Very adaptive: fast response to stimuli (pump more blood on need), robust behavior (restore its normal flow a few minutes later)
- The Heart structure
  - Non adaptive: once damaged, it cannot repair itself (e.g., think at heart attacks!)

# Adaptive Individuals vs. Adaptive Systems

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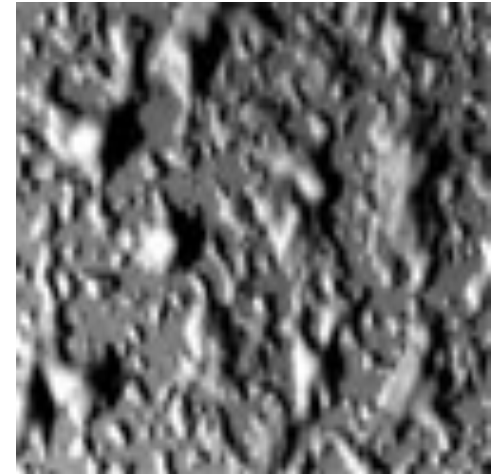
- Sometimes, individual may be adaptive
  - Cats can live anywhere and adapt their food habits accordingly
  - Chameleons change color depending on the environment
- Making the whole system consequently adaptive
  - Cat colonies live and prosper anywhere on the planet
- But sometimes individual capabilities the system overall may not
  - Chameleons communities strongly endangered by pollution and (guess what) by cats ☹️
  - The “dynamics” of the chameleons system outperforms the dynamics of the individuals



# Non Adaptive Individual vs. Adaptive Systems

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- In several cases, ensembles of very simple, purely “reactive” components, may overall lead to very adaptive systems
  - The cell of the heart are not per se adaptive or “smart”, nevertheless...
  - The simple unicellular components of the Dictyostelium group together to hunt
- In these cases, adaptivity is a capability that “emerges” from the system and from its interactions
  - Induced by the specific dynamical behavior of the system, as determined by the simple behavior of for the very fact of being a system with a specific dynamics
- Here, adaptivity is a consequence of complexity, and of the system being “at the edges of chaos”





# What are we Interested In?

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- All the discusses classes of adaptivity are of great interest to us (and will be analyzed)
  - “Smart” (hardware/software) components able to exhibit adaptivity as individuals (**agents**)
  - “Smart” components able to exhibit adaptivity in multicomponent systems (**multiagent systems**)
  - “Stupid” components able to exhibit collective adaptivity, i.e., they are collectively smart (**cellular automata, complex and social networks, swarm intelligent systems**)



# Adaptive Computing Systems

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- Let us now turn our attention to various computational systems, and see
  - why they have to be adaptive
  - how they can achieve adaptivity



# Computational Openness and Network Dynamics

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- Openness is a general characteristics of modern decentralized distributed systems
  - **Decentralization:** many stakeholders can add computers and components (e.g., Web pages and components). No central control.
  - **Mobility:** users/components move while being connected to the network (PDA, mobile phones, vehicles) so that the structure of the system continuously change
- Also, consumer and embedded computing systems
  - **Ephemeral:** Lead overall to very dynamic systems, with nodes coming on and away at any time





# Situatedness in Physical Environments

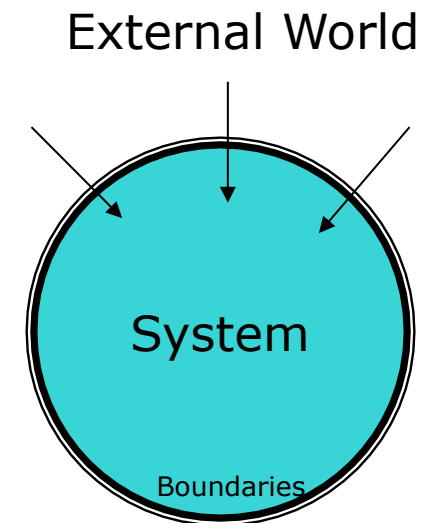
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- Modern computing systems are more and more made able to interact with the physical world
  - **Localization mechanism**, GPS
  - **Sensors and actuators** to understand and affect what is happening in the physical world
  - And this is definitely the case for mission critical systems
- Therefore, the physical world is becoming a central part in distributed computing
  - Location aware computations, that adapt their behavior depending on where the user is
    - A Service that adapt the information provided to vehicles depending on their location
  - Situation-aware services:
    - a smart user interface that adapt its lightening depending on the external visibility
    - A security sensor that recognize illegal activities in a park and alert the police
  - More generally, “ambient intelligent” systems

# Dealing with Openness and Dynamics

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- Let's "model" explicitly
  - What it is inside the system
  - What it outside (entities and perturbation forces)
- Identify and model the "interactions across boundaries"
  - What comes in goes out
  - How the environment can change
  - Sources of structural dynamics
- The boundaries of the system somewhat identify the "**environment**" or (which is the same) the "**context**" in which the system situated and its dynamics
  - The environment is an abstraction!!!
  - Not always easy to identify





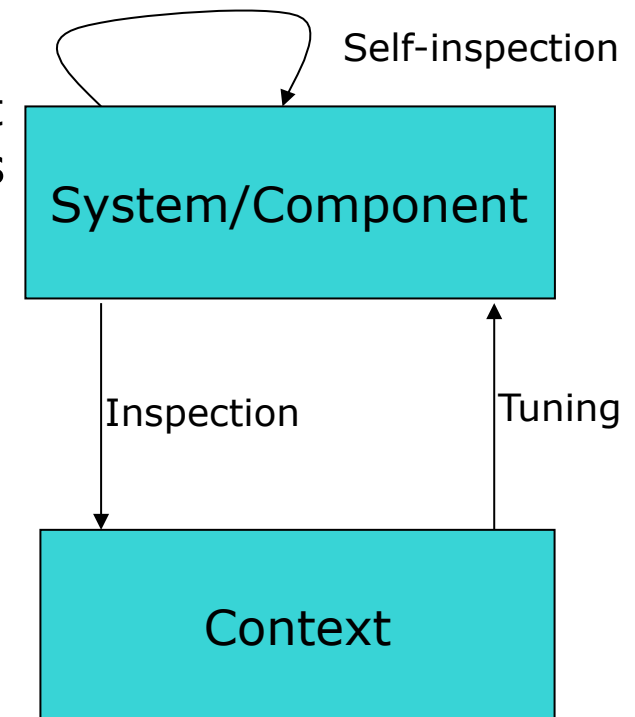
# Context-awareness

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- More in general, for computing to be adaptive it has to be
  - **Context-Aware and context-adaptive**
- Which implies
  - The system or its components must be able to recognize the context in which they situate
    - A computational context (the set of file, services, communication and computation resources, as e.g., in servlet context)
    - A physical context (the real-world)
  - Must recognize changes in context
  - Must adapt their behavior to changes in such context
- This can be achieved either via the adaptivity capability of the individuals, or via the adaptive capability of the system as a whole
- So, it is rather clear that adaptivity may be strictly related to the overall dynamics and complexity of a system...

# Adaptivity via Context-awareness

- In general, it is achieved via
  - Inspection of the context
  - Tuning of behavior depending on context
- This can occur at the level of individuals or at the level of the system
  - And it can include “self-inspection”
  - the systems and its component are by definition part of the context
- It can be supported by proper technologies to help recognizing context and properties of the system
  - “middleware” in the end is something that enables context-awareness and adaptivity...
- **Agents** (discussed in later lessons) are **inherently context-aware** components
- But here in this course we are also interested in something more: **adaptivity via dynamic self-organization in complex systems!**





## Part 3

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- What is a Complex System?



# What is a Complex System?

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- A system is complex when it is hard to infer its dynamics from the behavior and state of its individual components → difficult or impossible to detect its evolution in the phase space
- There are various reasons for this:
  - **Local interactions:** usually, interactions occur among a limited set of “neighbor” components, so that their global transitive effect on the global system state is hard to be elaborated
  - **Non linear dynamics:** e.g.,  $x(t+1) = x(t)(1-x(t))$
  - And **feedbacks in interactions:**  $A \rightarrow B, B \rightarrow A$ ,
    - Both typically leading to equations difficult to solve, and to complex phase space topologies with multiple complex attractors. For instance, a system can evolve in very differentiated ways even from very close initial points in the phase space (“butterfly effect”).
  - **Openness and Environmental Dynamics:** these prevent
    - A definite modeling of the system, as the system keeps on changing
    - Any predictive modeling of the behavior. The system is always kept out of equilibrium, so that it is difficult to simply try to see how a system will evolve in the phase state diagram. Probabilistic models must be considered



# Complex vs. Complicated Systems

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- Clearly, in nature and engineering there are many systems which are very complicated
  - Many components, many interactions
- However, a system which is only complicated and not complex typically has
  - Linear interactions, facilitating modeling and integration of dynamical equations
  - No feedback loops, avoiding the butterfly effect
  - A single or a limited set of stable equilibrium points or limit cycles
  - Contiguous points in the phase space attracts towards the same attractors
  - It is closed, or has well defined boundaries with predictable interactions across boundaries. So it can be treated deterministically
- Example:
  - The engine of a car can be very complicated, but it is not complex
    - A turbo engine can become complex (the feedback cycle induced by the turbo injector)
    - A badly cooled system can become complex, due to the thermodynamic interactions with the external world
  - A microprocessor, even with billion transistors, it typically only “complicated” → very linear and clean transition rules



# Complex Distributed Computational Systems

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- Most modern distributed computational systems are indeed complex
- They are open and situated, which is per se an important driving force for complexity
  - We have analyzed this w.r.t. adaptivity
- In addition, they are often based on local interactions
  - E.g., P2P system, mobile systems
- Interactions are not linear
  - E.g., in the Web, the time to get a service grows more than linearly with the number of concurrent requests
  - Effects such as TCP timeouts introduce non-linearity
  - The behavior of humans is greatly non-linear, necessarily reflecting the network system
- And they contain feedback loops
  - The network has loops
  - The more we wait for a service, the more we keep on polling (reinforcement feedback)
  - In P2P network, the more the users the more the system grows and get used






# Complexity vs. Size

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- Size (the number of components in a system) per se, is not a key reason for complexity
  - There are several huge systems which are simple and linear
  - Control hierarchies, engines, microprocessors
- However, size may be a necessary pre-condition for complexity
  - E.g., Two gravitational masses cannot be a complex system, Three masses are (the three body problem), Asteroids in the Kuiper belt are subject to complex movements
- For Distributed Computational Systems
  - The size may be so large that complexity can hide in them
  - In general, size (together with decentralization) prevents a complete micro-level knowledge of its local components state, e.g., it is nearly impossible to know exactly all the peers in Kazaa



# Equilibrium, Chaos, and the Edges of Chaos

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- It is important to note that a complex system is not necessarily chaotic
- Rather, many types of complex systems found in nature are at the “edge” of order and chaos: critical order
  - **Order**: global equilibrium of the system, uniformity
  - **Chaos**: disordered out-of-equilibrium behavior, unorganized non-uniformity
  - **Edges**: out-of-equilibrium, organized and structured behavior, although not exactly predictable
- Clearly, changing some working parameter of the system may lead it to become ordered or chaotic...
- Please note that the “chaos” word often refers to systems that are subject to the butterfly effect (e.g., the Earth atmosphere).
  - However, the butterfly effect does not imply that the system is chaotic, but simply that
  - It can evolve in very different configurations starting from however close initial conditions



# Complexity vs. Chaos: Examples

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- A Dead Heart
  - Static equilibrium, total order
- A Health Heart
  - Global synchronization pattern (order!) of its cells, achieved via local interactions and feedbacks
  - However, the synch is never so exact, and may slightly vary in period
  - Edges of chaos...
- A Heart during an attack
  - Fibrillation, chaotic pulsing of its cells



# Self-organization in Nature

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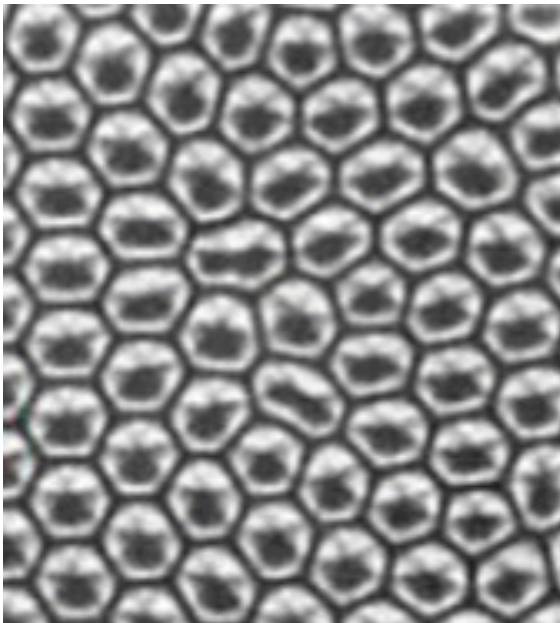
- Many natural systems – even when composed of very simple or stupid elements, appears able to self-organize themselves

*“Self-organization is a process in which pattern at the global level of a system emerges solely from numerous interactions among the lower level components of the system”. [Deneubourg 1977]*

- Actually, these systems exhibit a behavior which is clearly at the edge between order and chaos
- In most cases, due to the presence of non-linearity and both positive and negative feedbacks
  - Positive feedbacks introduce amplifications and move the system out of equilibrium
  - Negative feedbacks self-regulate the system and avoid it to become chaotic
- The behavior is considered “emergent”

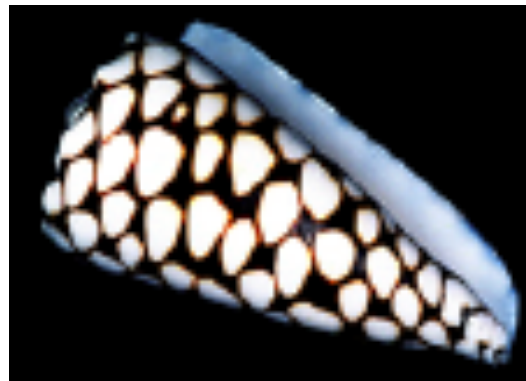
# Examples of Self-organization in Nature (1)

- Patterns in Physics



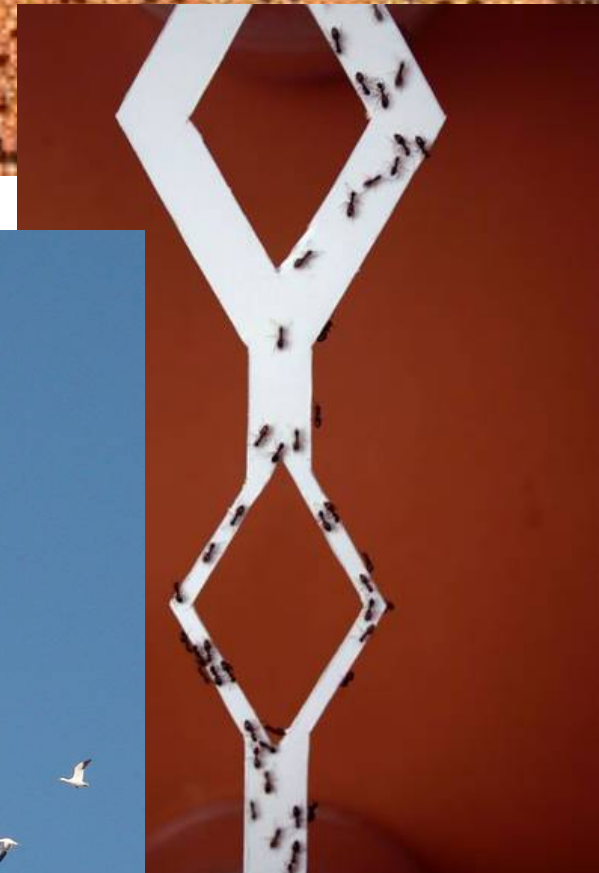
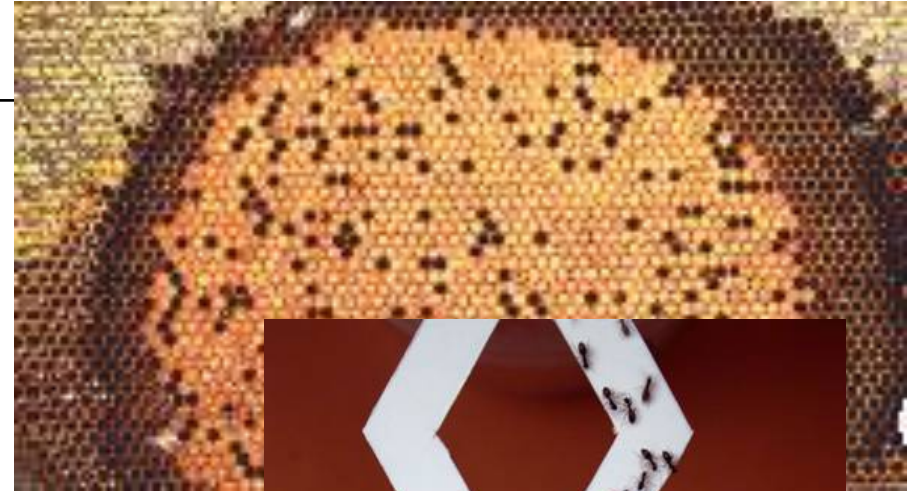
# Examples of Self-organization in Nature (2)

- Patterns in Skins and Shells



# Examples of Self-organization in Nature (3)

- Dynamic Patterns in Group Behavior





# Examples of Self-organization in Nature (4)

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- Emergent Behaviors in Societies
  - Clapping synchronization
  - Mexican Wave (“La Ola”)
  - Patterns of Walking in crowded pathways
  - Patterns of epidemics
  - Patterns of acquaintances
- The structure of networks
  - Many networks of different kinds (nature, society, technology)
  - Tend to evolve such as to self-organize specific structure
  - Adaptive and robust w.r.t. to both structure and information propagation





# Complexity vs. Adaptivity

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- A self-organized system may be adaptive for a wide range of environmental perturbations
  - It can re-establish global patterns upon changed conditions
  - Typically not the same, but similar
  - It moves from an attractor to an equivalent one
- The presence of negative feedbacks, provide for re-establishing order
- Clearly, excessive perturbations may disrupt the system or move it to chaotic state
  - E.g., the human heart
- Also, openness is a limited problem
  - New components can get in the system
  - Without affecting significantly its overall dynamics



## Part 4

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- Why Exploiting CAS in Modern Distributed Systems?



# What Characterize Modern Distributed Systems?

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- Large, decentralized, situated and dynamics networks
  - Internet, Web, P2P, sensor networks, WiFi meshes
- High complexity of software and underlying hardware
  - very hard to be managed and engineered, due to size and non linear interactions
- Continuous updated and tuning needed
  - Dynamic changes in the network and in the system (openness), as well in the patterns of usage
  - Dynamic changes in the environment
- Impossibility of direct control and configuration
  - E.g., cannot control all the nodes of the Internet or of a P2P network
  - Cannot control and access all the sensors and embedded computers distributed in an environment
- Impossibility of direct maintenance
  - Cannot re-configure manually all the nodes
  - Application must not stop working and should preserve specific quality levels



# Why Self Organization in Distributed Systems? Also...

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- Commercial and Practical Reasons
- And even if we could control the configuration and the adaptation/maintenance of complex systems that would be
  - Economically unfeasible
    - Too high development and maintenance costs
  - Commercially unacceptable
    - Who wants a system which is always in need of configuration?
- Computing systems must become
  - Proactive, self-adapting and self-organizing with “humans out-of-the-loop” (Tennenhouse, 2001)
  - Autonomic, as if they were living organisms (Kephart, 2003)
  - Easy and painless to be used as “sprays” (Zambonelli, 2005)



# What is Computational Self-Organization?

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- Components/applications get deployed and:
  - They recognize who and where they are (w.r.t. the other components and the environment)
  - They identify their specific task in the network (according to the who and where)
  - They start working in cooperation with the other components to achieve their task
  - The global goal/configuration reached without supervision
  - Achieving in a spontaneous way **emergent, self-organized, coherent behaviors**
- Upon dynamic changes
  - They recognize such changes
  - And re-adapt to suit the new situation



# So What?

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- There is need for brand new:
  - Theoretical models
  - Algorithms
  - Middleware infrastructures
  - Programming abstractions
  - Methodologies and tools
- For building distributed computing systems that can
  - Show properties of natural complex adaptive systems
  - Rely on self-organization and emergent organization
  - Be robust to dynamics and be highly adaptive
- A great commercial advantage could be achieved in current applications
  - Faster deployment, reduced configuration and maintenance costs, natural evolution
- And a number of potential innovative applications could be conceived and deployed....